

Profibus® D. P. Control Logic Card



Models

DPC-100 12 or 24 Volt D.C. Actuators

Application

Protocol: Profibus® DP (Distributed Process)

For on/off or positioning control of motorized valves, it also serves as the vital intelligence link between PLC's in the control room and the actuators in the field. Up to 126 actuated valves can be controlled on a single network. The automatic calibration feature requires no loop tuning. All operating parameters can be set from the communications center over the bus.

Features

- Two wire control reduces installation and start up time compared to multi-cable wiring.
- Automatic calibration cuts down on start up time.
- No deadband eliminates need for field adjustments.





- On line configuration of 36 operational parameters using generic Profibus[®] software.
- Low power consumption; does not require ventilation.
- Electronic overload protection with built-in current monitoring.
- LED indicators for input, outputs and communication channel.
- Automatic calibration with local pushbutton or remote command.
- Dynamic breaking eliminates overshooting.
- Robust power switching components, designed specifically for actuator motors, virtually eliminates field failures.

Specifications

Power Supply

DPC-100: 24/12VDC **DPC-120:** 120VAC

Communication Interface

Profibus® Standard

Protocol

Profibus[®] DP (Distributed Process)

Feedback

Potentiometer 1000 Ohms/Optical Encoder

Position Input Accuracy

1.0% full scale standard, Maximum 0.1%

Temperature

-40°C to +70°C (-40°F to +158°F)

Relative Humidity

0 to 90% non-condensing

Dimensions

DPC-100:4.0 x 1.5 x 2.5 in.**DPC-120:**4.25 x 1.75 x 3.75 in.

The DPC-100 & DPC-120 provide the following status and fault signals:

Valve full closed Valve full open Percentage of open Valve seeking position Motor running Valve closing Valve opening Motor thermostat tripped Incomplete travel Valve opening or closing manually Valve jammed/current limiting Motor still energized after stop or end of travel Controller self-test (detects problems) Communication failure Average running current load Peak running current load Idle current load



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